One- and two-hand devices Safeball™





A two-hand device which is comfortable and easy to use.

Approvals:



Safeball for:

- Presses
- Punches
- Fixtures
- Shearing machines

Features:

- Ergonomic
- Low activation force
- Flexible mounting
- Several grip possibilities
- Highest safety level
- Two channel switching in each hand
- Available for AS-i

Safeball™ Unique World Wide Two-hand device

Safeball[™] consists of a spherical ball containing two embedded pushbutton switches, one on each side of the ball. By using this pushbutton configuration, the risk of unintentional activation is minimised and the device is simple and ergonomic to use.

Safeball[™] can be utilised for either One-hand (one Safeball[™]) or Two-hand (two Safeballs[™]) applications. In either application, and in order to meet the required level of safety, the Safeball[™] switches are monitored by specified/certified ABB Jokab Safety Safety relays (see electrical connection).

In the case where Two-hand control is used, both Safeballs[™] i.e. all four pushbuttons have to be activated within 0.5 seconds. If one or more pushbuttons are released a Stop signal is given to the machine. In order to provide the highest level of safety the Safeball[™] design provides the operator with a dual switching function and short-circuit supervision in each hand.

Each Safeball[™] is ergonomically designed and has both its cover and actuator made of environmentally-friendly polypropylene. The design allows for comfort of use for all hand sizes and operation from numerous gripping positions. Mounting of the Safeball[™] is also very flexible allowing the device to be mounted in the most ergonomic position for the operator.

When can a Two-hand or One-hand control be used?

A Two-hand control can be used when it is necessary to ensure that the operator is outside and must be prevented from reaching into the hazardous area. If the operator decides, after the start signal has been given to the machine, to make an 'after-grasp' i.e. try to adjust the part that has been placed into the machine, then a dual stop signal is given to the machine.

An One-hand control device can be used when the operator cannot reach the hazardous area with his/her free hand or on less dangerous machines.

Highest Safety Level

The Safeball[™] is certified by Inspecta in Sweden for use as a Two-hand control device, when used with a JSBR4 ABB Jokab Safety Safety relay or Pluto Safety-PLC, in accordance with the highest safety level in standard EN 574 (type IIIc).

Safeball adapted for AS-i

Safeball also comes in a version adapted for direct attachmenent to the AS-i bus. For using the safeball AS-i as a Two-hand device the AS-i safety monitor needs to be able to handle simultaneous monitoring off the channels.

Safeball Function

Two-hand control device

The Two-hand control device is implemented by using two Safeballs[™], each having two internal pushbuttons. The Safeballs[™] must be mounted a minimum distance between each other (see Mounting description).

By utilising two pushbuttons in each device a double safety function is provided in each hand.

The highest safety level is achieved by connecting all four pushbuttons to the ABB Jokab Safety JSBR4 safety relay or Pluto Safety-PLC. The safety relay gives a dual and supervised safety function and requires input activation within 0.5 seconds in order to start the machine. It also checks that all four pushbuttons have returned to their deactivated positions before a new start is allowed. The JSBR4 safety relay also provides a stop signal if one or more pushbuttons are released.

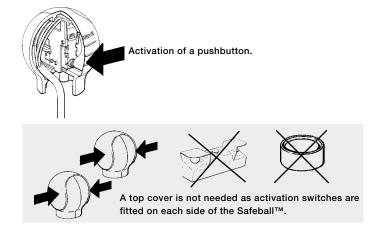
One-hand control device

Safeball[™] is also a very practical method of providing a one-hand control device as it is very easy to find and activate by the machine operator. One-hand devices should only be used when the operator cannot reach into the hazardous area with his/her free hand or on less dangerous machines. Before fitting the necessary risk assessment must be made to determine suitability of this type of control. To achieve the highest safety level for One-hand control the Safeball[™] must be connected to a safety control system (E.g. safety relay or safety PLC).

Versions

Safeball is available in several versions to meet different mounting requirements.

JSTD1-A - Safeball 1 NO + 1 NC with 2 m cable JSTD1-B - Safeball 1 NO + 1 NC with 0.2 m cable JSTD1-C - Safeball 1 NO + 1 NC with 10 m cable JSTD1-E - Safeball 2 NO 0.2 m cable JSTD1-G - AS-i Safeball



| Article number | |
|------------------------------|--|
| JSTD1-A | 2TLA020007R3000 |
| JSTD1-B | 2TLA020007R3100 |
| JSTD1-C | 2TLA020007R3200 |
| JSTD1-E | 2TLA020007R3400 |
| JSTD1-G AS-i | 2TLA020007R3900 |
| Material | Polypropylene |
| Colour | Yellow and black |
| Size | Height: approx. 71 mm |
| | Diameter, min.: 68 mm |
| | Diameter, max.: 72 mm |
| | Diameter, base: 42 mm |
| Weight | 0.2 kg with 2 m cable |
| | 0.7 kg with 10 m cable |
| | 0.1 kg with 4x0.2 m wires |
| Level of Safety | |
| EN ISO 13849-1 | Up to PL e/Cat. 4 |
| Ambient temperature | -25°C to +50°C (operating) |
| Protection class | IP67. Not intended for use under |
| | water |
| Operating force | Approx. 2 N |
| Actuator travel | 1.3 +/- 0.6 mm |
| Max switching load | 30 V 2A DC, resistive load |
| Max current (resistive load) | 2 A at 30 VDC (max) |
| | 20 mA at 24 VDC (recommended) |
| Min switching load | 6V 10mA DC, resistive load |
| Contact resistance | 100 mohm |
| Life, mechanical | > 1x10 ⁶ operations at max. 1 Hz |
| Life, electrical | Dependant upon electrical load |
| | characteristics |
| Connection cable | |
| JSTD1-A | 2 m PVC-cable, 4 x 0.75mm ² |
| JSTD1-B, JSTD1-E | 4 x 0.75 mm ² wires, approx. 0.2 m |
| JSTD1-C | 10 m PVC-cable, 4 x 0.75 mm ² |
| JSTD1-G AS-i | $2 \times 0.75 \text{ mm}^2$ wires, approx. 0.25 m |
| Conformity | EN ISO 12100:2010 |
| | EN 574+A1:2008 |

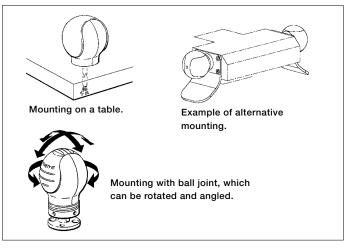
| Chemical resistance at 20°C | |
|---|------------|
| Chemical | Resistance |
| Alcohols | good |
| Paraffin oil | good |
| Milk | good |
| Silicon oil | good |
| Acetone | good |
| Please contact us for more information. | |

Safeball Mounting

The Safeballs[™] can be mounted in many different ways. They can be mounted on a table, a machine, on a support or wherever suitable for ergonomic reasons. The Safeball[™] can be mounted in a fixed position or on a tilting and/or rotating support. This flexibility of mounting permits the Safeball[™] to be fitted in the best ergonomic position for the ease of operation by the operator. The distance requirement between two Safeballs[™] or between a Safeball[™] and a wall or edge of a table depends on how the Safeball[™] is mounted. Safeball[™] can be mounted with four M5 screws or ST4.8 self-tapping screws.

NOTE! When Safeballs[™] are mounted in such a way that the distance between them can be adjusted to less than the specified minimum, the mounting screws must be locked to ensure any changes in the distance between the two balls cannot be made.

Alternative mounting methods



Approved Two-hand device

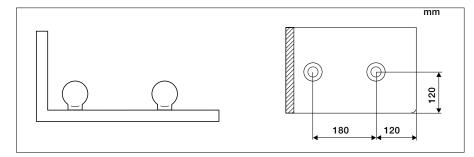
To be an approved Two-hand device, both Safeballs[™] must be mounted a minimum distance apart in order to prevent operation of both balls with one hand. Safeballs[™] must be fitted a minimum distance from the edges of tables or a wall. It is essential that Safeballs[™] are correctly installed in order to prevent unintended activation of the devices with part of the body in combination for example with a wall.

Mounting distance - Safety distance - Safeball

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Mounting distance

Table mounting of two Safeballs[™]. In order to prevent cheating the distances shown are the minimum allowed.

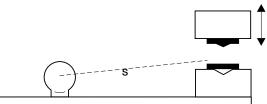


Safety distance

The Safety distance is the distance between the Safeballs[™] and the dangerous machine movement. The safety distance requirement can be calculated using the following formula for Safeball[™] in accordance with the approving authority and EN ISO 13855: S= KxT+C

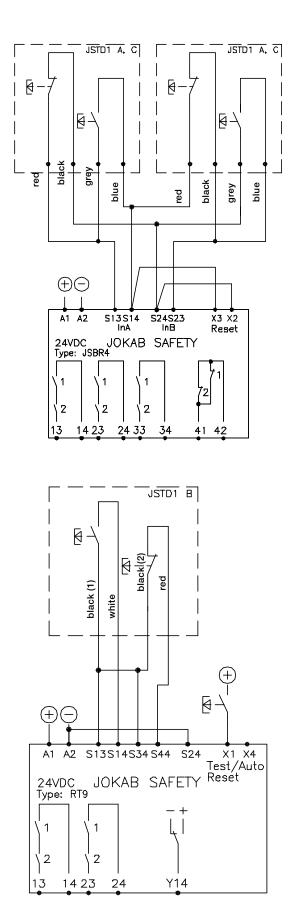
Where

- S = safety distance in mm
- K = hand speed, 1600 mm/s
- T = total stopping time for the dangerous movement (including the response time of the safety relays in seconds)
- C = Constant = 0 mm for Safeball.



The safety distance is the distance between the Safeballs™ and the dangerous machine movement. Note that S must never be less than 100 mm.

Safeball Electrical connection



Two-hand device

Safeballs[™] are designed to be connected to a ABB Jokab Safety JSBR4 Safety relay or Safety PLC to achieve the highest safety requirements for a Two-hand device.

Example of two devices connected to a ABB Jokab Safety JSBR4 safety relay. Response time on receiving a stop signal from JSTD1 < 15 ms.

One-hand device

When used as a One-hand device the Safeball[™] is designed to be connected to a ABB Jokab Safety RT6, RT7 or RT9 Safety relay in order to achieve the highest possible safety level for this type of control.

Example of a single Safeball[™] connected to a ABB Jokab Safety relay RT9. The response time at 'stop' is < 20 ms.