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## Main

Range of product	Altivar Process ATV600
Product or component type	Variable speed drive
Product specific application	Process and utilities
Device short name	ATV630
Variant	Standard version
Product destination	Asynchronous motors Synchronous motors
EMC filter	Without EMC filter
IP degree of protection	IP20IEC 61800-5-1 IP20IEC 60529
Degree of protection	UL type 1 UL 508C
Type of cooling	Forced convection
Supply frequency	50...60 Hz - 5...5 %
Phase	3 phase
[Us] rated supply voltage	600 V - 15...10 %
Maximum Horse Power Rating	30 Hp 600 V normal duty 25 hp 600 V heavy duty
Line current	26.9 A 600 V normal duty) 23.2 A 600 V heavy duty)
Prospective line Isc	70 kA
Apparent power	28 KVA 600 V normal duty) 24.1 kVA 600 V heavy duty)
Continuous output current	34 A 4 kHz normal duty 27 A 4 kHz heavy duty
Maximum transient current	37.4 A 60 s normal duty) 40.5 A 60 s heavy duty)
Asynchronous motor control profile	Optimized torque mode Variable torque standard Constant torque standard
Synchronous motor control profile	Permanent magnet motor Synchronous reluctance motor
Speed drive output frequency	0.1...599 Hz
Nominal switching frequency	4 kHz
Switching frequency	2...8 kHz adjustable 4...8 kHz with derating factor
Safety function	STO (safe torque off) SIL 3
Discrete input logic	16 preset speeds
Communication port protocol	Modbus TCP Modbus serial Ethernet
Option card	Slot A communication module, Profibus DP V1 Slot A communication module, Profinet Slot A communication module, DeviceNet Slot A communication module, Modbus TCP/ EtherNet/IP Slot A communication module, CANopen daisy chain RJ45 Slot A communication module, CANopen SUB-D 9 Slot A communication module, CANopen screw terminals Slot A[slot B digital and analog I/O extension module Slot A[slot B output relay extension module Slot A communication module, Ethernet IP/Modbus TCP/MD-Link Communication module, BACnet MS/TP Communication module, Ethernet Powerlink

## Complementary

Output voltage	<= power supply voltage
Permissible temporary current boost	1.1 x In 60 s normal duty) 1.5 x In 60 s heavy duty)
Motor slip compensation	Can be suppressed Automatic whatever the load Not available in permanent magnet motor law Adjustable
Acceleration and deceleration ramps	Linear adjustable separately from 0.01...9999 s S, U or customized
Braking to standstill	By DC injection
Protection type	Thermal protection motor Safe torque off motor Motor phase break motor Thermal protection drive Safe torque off drive Overheating drive Overcurrent between output phases and earth drive Overload of output voltage drive Short-circuit protection drive Motor phase break drive Overvoltages on the DC bus drive Line supply overvoltage drive Line supply undervoltage drive Line supply phase loss drive Overspeed drive Break on the control circuit drive
Frequency resolution	Display unit 0.1 Hz Analog input 0.012/50 Hz
Electrical connection	Control removable screw terminals 0.5...1.5 mm <sup>2</sup> AWG 20...AWG 16 Motor screw terminal 10 mm <sup>2</sup> AWG 8 Line side screw terminal 10 mm <sup>2</sup> AWG 8
Connector type	RJ45 on the remote graphic terminal)Ethernet/Modbus TCP RJ45 on the remote graphic terminal)Modbus serial
Physical interface	2-wire RS 485 Modbus serial
Transmission frame	RTU Modbus serial
Transmission rate	10/100 Mbit/s Ethernet IP/Modbus TCP 4.8, 9.6, 19.2, 38.4 kbit/s Modbus serial
Exchange mode	Half duplex, full duplex, autonegotiation Ethernet/Modbus TCP
Data format	8 bits, configurable odd, even or no parity Modbus serial
Type of polarization	No impedance Modbus serial
Number of addresses	1...247 Modbus serial
Method of access	Slave Modbus TCP
Supply	External supply for digital inputs 24 V DC 19...30 V), <1.25 mA overload and short-circuit protection Internal supply for reference potentiometer (1 to 10 kOhm) 10.5 V DC +/- 5 %, <10 mA overload and short-circuit protection Internal supply for digital inputs and STO 24 V DC 21...27 V), <200 mA overload and short-circuit protection
Local signalling	Local diagnostic 3 LEDs Embedded communication status 3 LEDs dual colour) Communication module status 4 LEDs dual colour) Presence of voltage 1 LED red)
Maximum Width	9.69 in (246 mm)
Maximum Height	22.32 in (567 mm)
Maximum Depth	9.53 in (242 mm)
Net Weight	50.71 lb(US) (23 kg)
Analogue input number	3
Analogue input type	AI1, AI2, AI3 software-configurable voltage 0...10 V DC 30 kOhm 12 bits AI1, AI2, AI3 software-configurable current 0...20 mA/4...20 mA 250 Ohm 12 bits
Discrete input number	8
Discrete input type	DI1...DI6 programmable, 24 V DC <= 30 V)3.5 kOhm DI5, DI6 programmable as pulse input 0...30 kHz, 24 V DC <= 30 V) STOA, STOB safe torque off, 24 V DC <= 30 V> 2.2 kOhm

Input compatibility	DI1...DI6 discrete input level 1 PLC EN/IEC 61131-2 DI5, DI6 discrete input level 1 PLC IEC 65A-68 STOA, STOB discrete input level 1 PLC EN/IEC 61131-2
Discrete input logic	Positive logic (source) DI1...DI6), < 5 V, > 11 V Negative logic (sink) DI1...DI6), > 16 V, < 10 V Positive logic (source) DI5, DI6), < 0.6 V, > 2.5 V Positive logic (source) STOA, STOB), < 5 V, > 11 V
Analogue output number	2
Analogue output type	Software-configurable voltage AO1, AO2 0...10 V DC 470 Ohm 10 bits Software-configurable current AO1, AO2 0...20 mA 10 bits
Sampling duration	2 Ms +/- 0.5 ms DI1...DI4) - discrete input 5 Ms +/- 1 ms DI5, DI6) - discrete input 5 Ms +/- 0.1 ms AI1, AI2, AI3) - analog input 10 ms +/- 1 ms AO1) - analog output
Accuracy	+/- 0.6 % AI1, AI2, AI3 for a temperature variation 60 °C analog input +/- 1 % AO1, AO2 for a temperature variation 60 °C analog output
Linearity error	AI1, AI2, AI3 +/- 0.15 % of maximum value analog input AO1, AO2 +/- 0.2 % analog output
Relay output number	3
Relay output type	Configurable relay logic R1 fault relay NO/NC 100000 cycles Configurable relay logic R2 sequence relay NO 100000 cycles Configurable relay logic R3 sequence relay NO 100000 cycles
Refresh time	Relay output R1, R2, R3) 5 ms +/- 0.5 ms)
Minimum switching current	Relay output R1, R2, R3 5 mA 24 V DC
Maximum switching current	Relay output R1, R2, R3 resistive, cos phi = 1 3 A 250 V AC Relay output R1, R2, R3 resistive, cos phi = 1 3 A 30 V DC Relay output R1, R2, R3 inductive, cos phi = 0.4 7 ms 2 A 250 V AC Relay output R1, R2, R3 inductive, cos phi = 0.4 7 ms 2 A 30 V DC
Isolation	Between power and control terminals
Mounting mode	Wall mount

## Environment

Insulation resistance	> 1 MOhm 500 V DC for 1 minute to earth
Noise level	52 dB 86/188/EEC
Power dissipation in W	Natural convection 143 W 600 V 4 kHz Forced convection 495 W 600 V 4 kHz
Volume of cooling air	87178.34 Gal/hr(US) (330 m3/h)
Operating position	Vertical +/- 10 degree
Maximum THDI	<48 % with external line choke IEC 61000-3-12
Electromagnetic compatibility	Electrostatic discharge immunity test level 3 IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 IEC 61000-4-4 1.2/50 µs - 8/20 µs surge immunity test level 3 IEC 61000-4-5 Conducted radio-frequency immunity test level 3 IEC 61000-4-6
Pollution degree	2 EN/IEC 61800-5-1
Vibration resistance	1.5 mm peak to peak 2...13 Hz) IEC 60068-2-6 1 gn 13...200 Hz) IEC 60068-2-6
Shock resistance	15 gn 11 ms IEC 60068-2-27
Relative humidity	5...95 % without condensation IEC 60068-2-3
Ambient air temperature for operation	5...122 °F (-15...50 °C) without) 122...140 °F (50...60 °C) with derating factor)
Ambient air temperature for storage	-40...158 °F (-40...70 °C)
Operating altitude	<= 3280.84 ft (1000 m) without 1000...4800 m with current derating 1 % per 100 m
Environmental characteristic	Chemical pollution resistance class 3C3 EN/IEC 60721-3-3 Dust pollution resistance class 3S3 EN/IEC 60721-3-3
Standards	UL 508C EN/IEC 61800-3 EN/IEC 61800-5-1 IEC 61000-3-12 IEC 60721-3 IEC 61508 IEC 13849-1

Product certifications	UL REACH TÜV CSA
Marking	CE

### Ordering and shipping details

Category	22276 - ATV930 FRAMES 1 & 2
Discount Schedule	CP4E
GTIN	00785901015987
Package weight(Lbs)	23000 lb(US) (10432.62 kg)
Returnability	Yes
Country of origin	IN

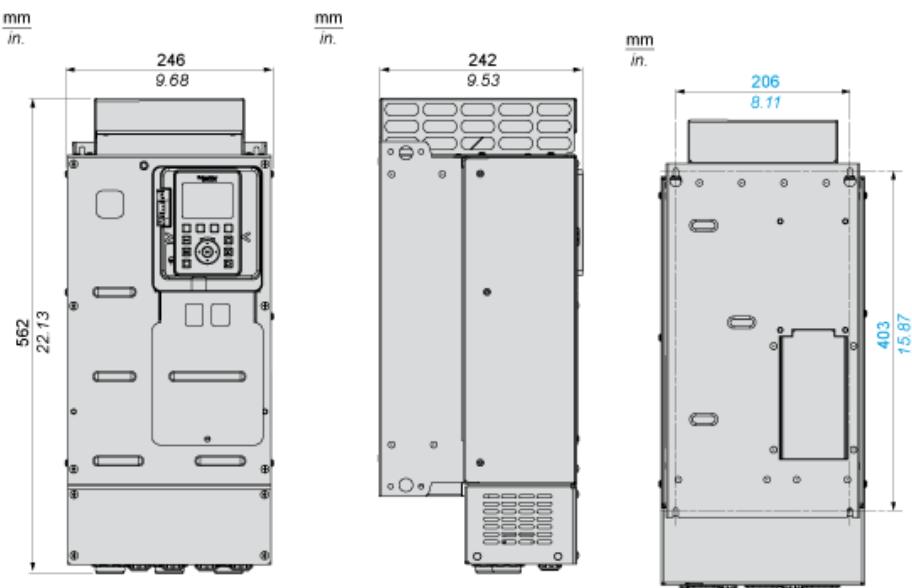
### Offer Sustainability

Sustainable offer status	Green Premium product
REACH Regulation	<input checked="" type="checkbox"/> REACH Declaration
EU RoHS Directive	Pro-active compliance (Product out of EU RoHS legal scope) <input checked="" type="checkbox"/> EU RoHS Declaration
Mercury free	Yes
RoHS exemption information	<input checked="" type="checkbox"/> Yes
China RoHS Regulation	<input checked="" type="checkbox"/> China RoHS Declaration
Environmental Disclosure	<input checked="" type="checkbox"/> Product Environmental Profile
Circularity Profile	<input checked="" type="checkbox"/> End Of Life Information
WEEE	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins.

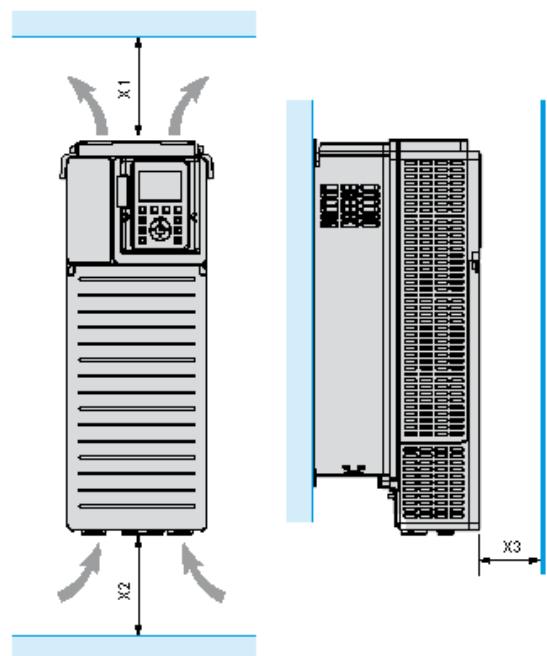
## Dimensions

### Drives with Top Cover

Front, Left and Rear Views



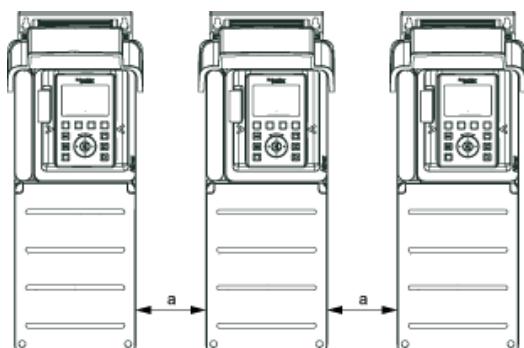
### Clearances



X1	X2	X3
$\geq 100 \text{ mm (3.94 in.)}$	$\geq 100 \text{ mm (3.94 in.)}$	$\geq 10 \text{ mm (0.39 in.)}$

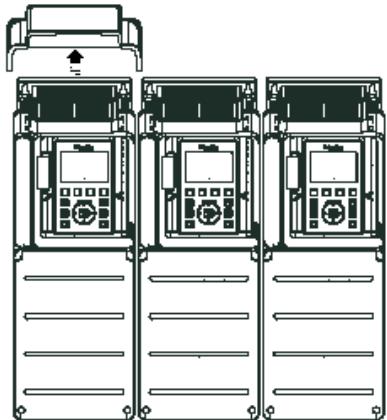
### Mounting Types

#### Mounting Type A: Individual IP21

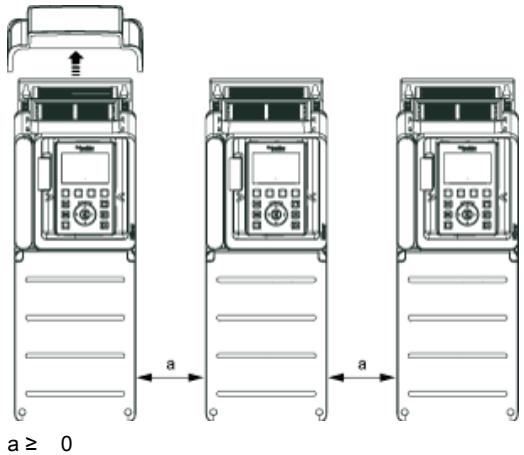


$a \geq 100 \text{ mm (3.94 in.)}$

## Mounting Type B: Side by Side IP20

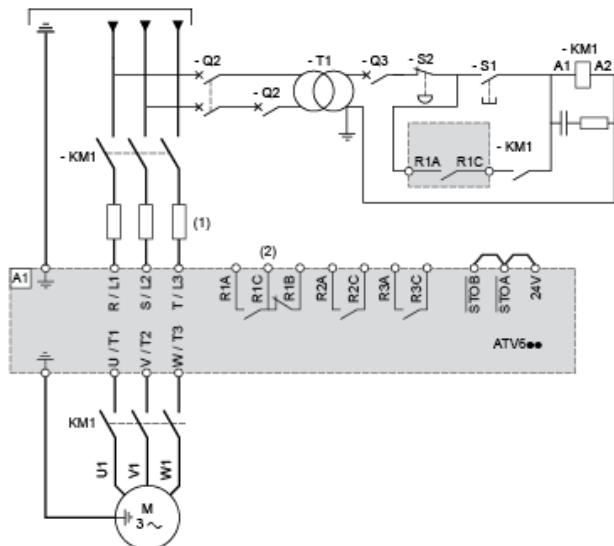


## Mounting Type C: Individual IP20



### Three-Phase Power Supply with Upstream Breaking via Line Contactor

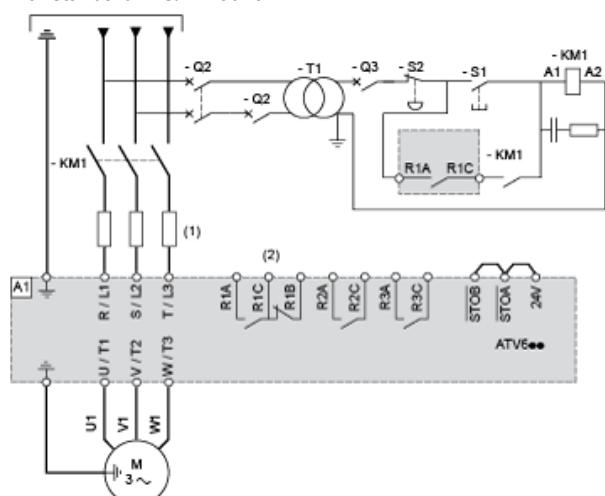
Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1



- (1) Line choke if used
  - (2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.
- A1 : Drive  
 KM1 Line Contactor  
 Q2, Circuit breakers  
 Q3 :  
 S1, Pushbuttons  
 S2 :  
 T1 : Transformer for control part

### Three-Phase Power Supply with Downstream Breaking via Contactor

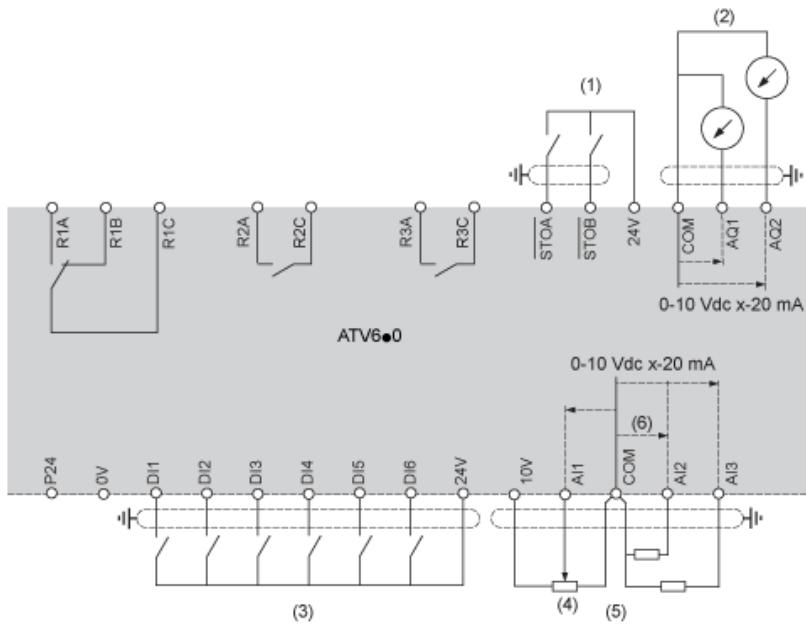
Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1



- (1) Line choke if used
  - (2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.
- A1 : Drive  
 KM1 Contactor

## Control Block Wiring Diagram

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- (1) Safe Torque Off
- (2) Analog Output
- (3) Digital Input
- (4) Reference potentiometer
- (5) Analog Input

R1A, Fault relay

R1B,

R1C :

R2A, Sequence relay

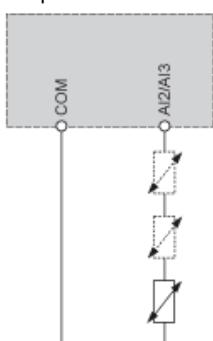
R2C :

R3A, Sequence relay

R3C :

### Sensor Connection

It is possible to connect either 1 or 3 sensors on terminals AI2 or AI3.



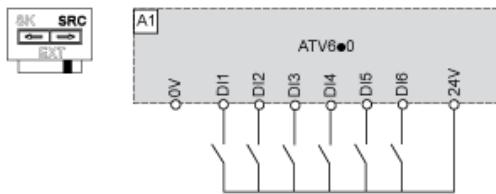
### Sink / Source Switch Configuration

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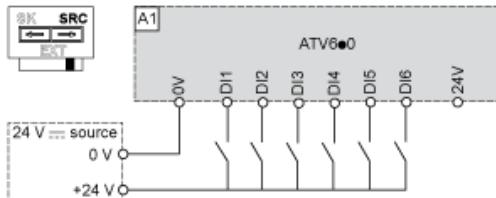
The switch is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs.

- Set the switch to Source (factory setting) if using PLC outputs with PNP transistors.
- Set the switch to Ext if using PLC outputs with NPN transistors.

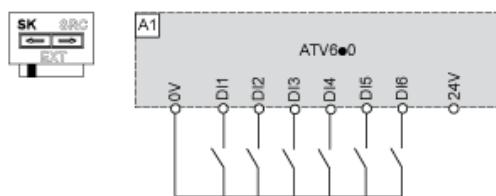
### Switch Set to SRC (Source) Position Using the Output Power Supply for the Digital Inputs



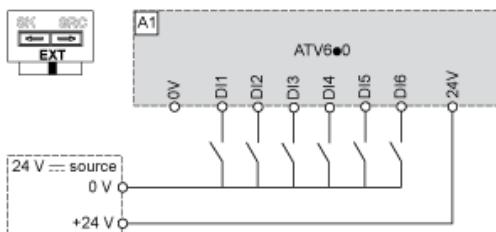
### Switch Set to SRC (Source) Position and Use of an External Power Supply for the DIs



### Switch Set to SK (Sink) Position Using the Output Power Supply for the Digital Inputs



### Switch Set to EXT Position Using an External Power Supply for the DIs



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Derating Curves

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