

TYPICAL MOTOR PERFORMANCE DATA

Model: 0304XDSC41A-P

HP	kW	Pole	FL RPM	Frame	Voltage	Hz	Phase	FL Amps
30	22	4	1770	286T	575	60	3	29
Enclosure	IP	Ins. Class	S.F.	Duty	NEMA Nom. Eff.	NEMA Design	kVA Code	Ambient (°C)
TEFC	56	F	1.15	CONT	93.6	B	G	40 C

Load	HP	kW	Amperes	Efficiency (%)	Power Factor (%)
Full Load	30	22.4	29.0	93.8	83.7
¾ Load	22.50	16.8	21.9	93.3	81.0
½ Load	15.00	11.2	16.3	91.7	73.8
¼ Load	7.50	5.6	11.9	85.2	55.3
No Load			10.1		5.3
Locked Rotor			172.00		34.4

Torque				Rotor wk ²
Full Load (lb-ft)	Locked Rotor (% FLT)	Pull Up (% FLT)	Break Down (% FLT)	Inertia (lb-ft ²)
89	185	165	290	5.70

Safe Stall Time(s)		Sound Pressure dB(A) @ 1M	Bearings*		Approx. Motor Weight (lbs)
Cold	Hot		DE	NDE	
35	15	-	6310C3	6310C3	

*Bearings are the only recommended spare part(s).

Motor Options:
Product Family:EQP Global 841
Mounting:Footed,Shaft:T Shaft

Customer	
Customer PO	
Sales Order	
Project #	

Tag:

All characteristics are average expected values.

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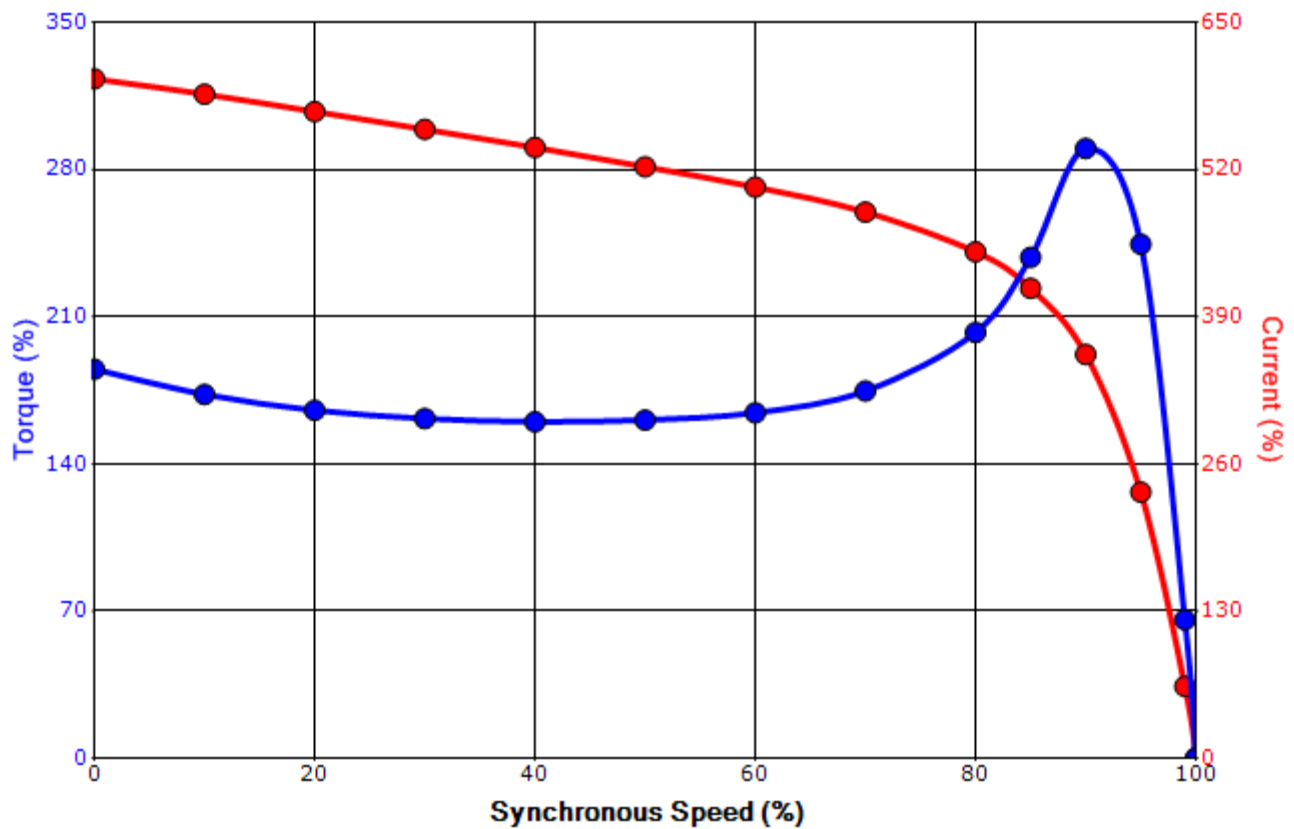
Engineering	jhock	Doc. Written By	D. Suarez	Doc.# / Rev	MPCF-1119 / 0
Engr. Date	3/13/2014	Doc. Approved By	M. Campbell	Doc. Issued	6/8/2011

SPEED TORQUE/CURRENT CURVE

Model: 0304XDSC41A-P

HP	kW	Pole	FL RPM	Frame	Voltage	Hz	Phase	FL Amps
30	22	4	1770	286T	575	60	3	29
Enclosure	IP	Ins. Class	S.F.	Duty	NEMA Nom. Eff.	NEMA Design	kVA Code	Ambient (°C)
TEFC	56	F	1.15	CONT	93.6	B	G	40 C
Locked Rotor Amps	Rotor wk ² Inertia (lb-ft ²)	Torque						Break Down (%)
		Full Load (lb-ft)	Locked Rotor (%)	Pull Up (%)				
172.00	5.70	89	185	165			290	

Design Values



Customer		wk ² Load Inertia (lb-ft ²)	-
Customer PO		Load Type	-
Sales Order		Voltage (%)	100
Project #		Accel. Time	-

Tag:

All characteristics are average expected values.

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Engineering	jhock	Doc. Written By	D. Suarez	Doc.# / Rev	MPCF-1121 / 0
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Motor Connection Diagram
3 Leads - Delta Connection



Switch L1 and L2 to reverse rotation

Each lead may consist of more than one cable.
If multiple cables represent a single lead, each one
of them will be labeled with the appropriate lead number.