

TYPICAL MOTOR PERFORMANCE DATA

Model: 0106XDSB47A-P

HP	kW	Pole	FL RPM	Frame	Voltage	Hz	Phase	FL Amps
10	7.5	6	1170	256TC	460	60	3	14
Enclosure	IP	Ins. Class	S.F.	Duty	NEMA Nom. Eff.	NEMA Design	kVA Code	Ambient (°C)
TEFC	56	F	1.15	CONT	91	B	G	40 C

Load	HP	kW	Amperes	Efficiency (%)	Power Factor (%)
Full Load	10	7.5	13.4	91.3	79.9
¾ Load	7.50	5.6	10.4	91.0	75.9
½ Load	5.00	3.7	8.4	89.4	66.2
¼ Load	2.50	1.9	7.0	81.7	40.9
No Load			5.5		
Locked Rotor			79.00		

Torque				Rotor wk² Inertia (lb-ft²)
Full Load (lb-ft)	Locked Rotor (% FLT)	Pull Up (% FLT)	Break Down (% FLT)	
44.9	260	255	290	2.65

Safe Stall Time(s)		Sound Pressure dB(A) @ 1M	Bearings*		Approx. Motor Weight (lbs)
Cold	Hot		DE	NDE	
29.1	20	-	6309C3	6309C3	

*Bearings are the only recommended spare part(s).

Motor Options:

Mounting:C-Face Footed,Shaft:T Shaft

Customer	
Customer PO	
Sales Order	
Project #	

Tag:

All characteristics are average expected values.

TOSHIBA INTERNATIONAL CORPORATION · HOUSTON, TEXAS U.S.A.

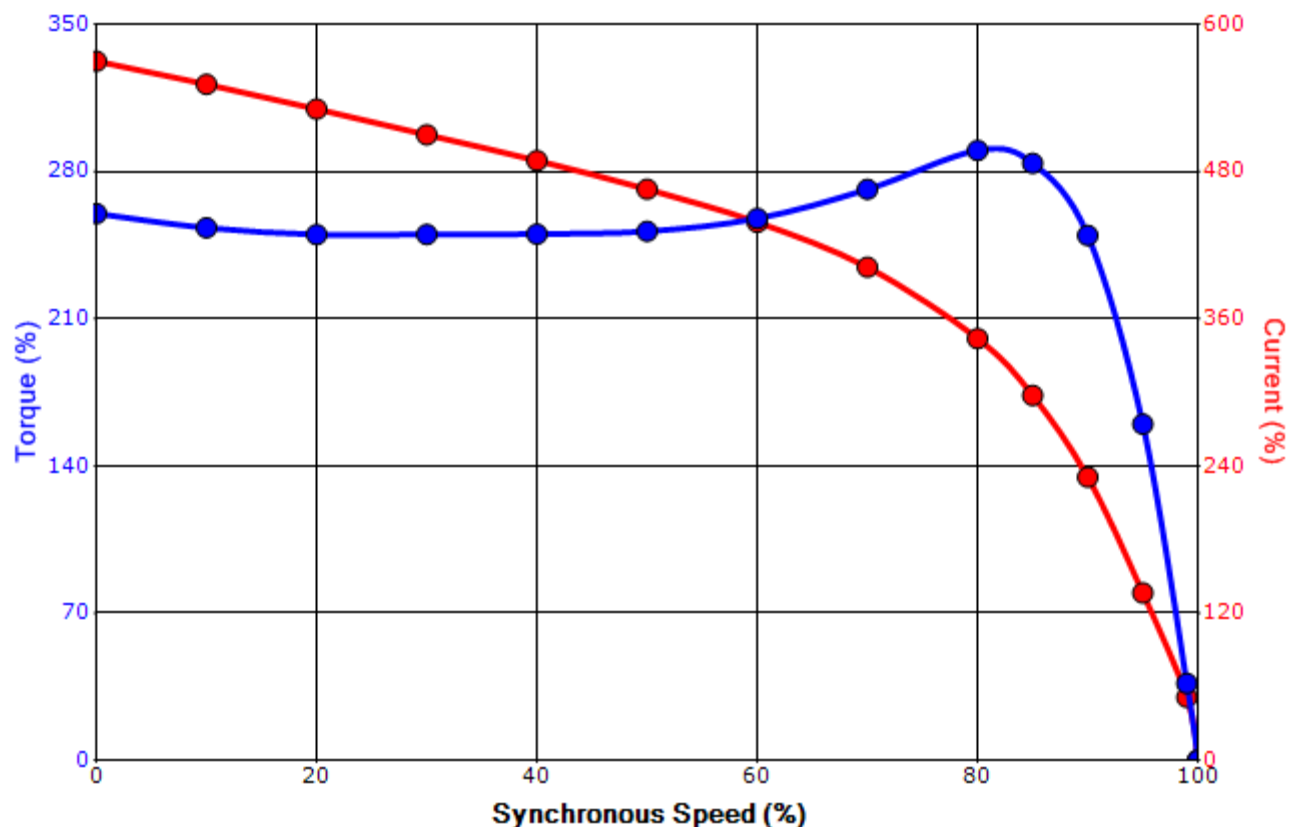
Engineering	jaustin	Doc. Written By	D. Suarez	Doc.# / Rev	MPCF-1119 / 0
Engr. Date	7/7/2014	Doc. Approved By	M. Campbell	Doc. Issued	6/8/2011

SPEED TORQUE/CURRENT CURVE

Model: 0106XDSB47A-P

HP	kW	Pole	FL RPM	Frame	Voltage	Hz	Phase	FL Amps
10	7.5	6	1170	256TC	460	60	3	14
Enclosure	IP	Ins. Class	S.F.	Duty	NEMA Nom. Eff.	NEMA Design	kVA Code	Ambient (°C)
TEFC	56	F	1.15	CONT	91	B	G	40 C
Locked Rotor Amps	Rotor wk ² Inertia (lb-ft ²)	Torque						
		Full Load (lb-ft)	Locked Rotor (%)	Pull Up (%)		Break Down (%)		
79.00	2.65	44.9	260	255		290		

Design Values



Customer			wk ² Load Inertia (lb-ft ²)	-
Customer PO			Load Type	-
Sales Order			Voltage (%)	100
Project #			Accel. Time	-

Tag:

All characteristics are average expected values.

TOSHIBA INTERNATIONAL CORPORATION · HOUSTON, TEXAS U.S.A.

Engineering	jaustin	Doc. Written By	D. Suarez	Doc.# / Rev	MPCF-1121 / 0
Engr. Date	7/7/2014	Doc. Approved By	M. Campbell	Doc. Issued	6/8/2011

Motor Connection Diagram

3 Leads - Delta Connection



Switch L1 and L2 to reverse rotation

Each lead may consist of more than one cable.
If multiple cables represent a single lead, each one
of them will be labeled with the appropriate lead number.