

TYPICAL MOTOR PERFORMANCE DATA

Model: 0056XDSC44A-P

HP	kW	Pole	FL RPM	Frame	Voltage	Hz	Phase	FL Amps
5	3.7	6	1160	215TC	575	60	3	5.50
Enclosure	IP	Ins. Class	S.F.	Duty	NEMA Nom. Eff.	NEMA Design	kVA Code	Ambient (°C)
TEFC	56	F	1.15	CONT	89.5	B	J	40 C

Load	HP	kW	Amperes	Efficiency (%)	Power Factor (%)
Full Load	5	3.7	5.5	89.6	78.0
¾ Load	3.75	2.8	4.1	89.8	73.3
½ Load	2.50	1.9	3.2	88.3	63.1
¼ Load	1.25	0.9	2.6	81.5	42.8
No Load			2.5		5.4
Locked Rotor			36		46.0

Torque				Rotor wk² Inertia (lb-ft²)
Full Load (lb-ft)	Locked Rotor (% FLT)	Pull Up (% FLT)	Break Down (% FLT)	
22.6	185	175	325	1.32

Safe Stall Time(s)		Sound Pressure dB(A) @ 1M	Bearings*		Approx. Motor Weight (lbs)
Cold	Hot		DE	NDE	
35	15	-	6308C3	6308C3	0

*Bearings are the only recommended spare part(s).

Motor Options:

Mounting:C-Face Round,Shaft:T Shaft

Customer		
Customer PO		
Sales Order		
Project #		

Tag:

All characteristics are average expected values.

TOSHIBA INTERNATIONAL CORPORATION · HOUSTON, TEXAS U.S.A.

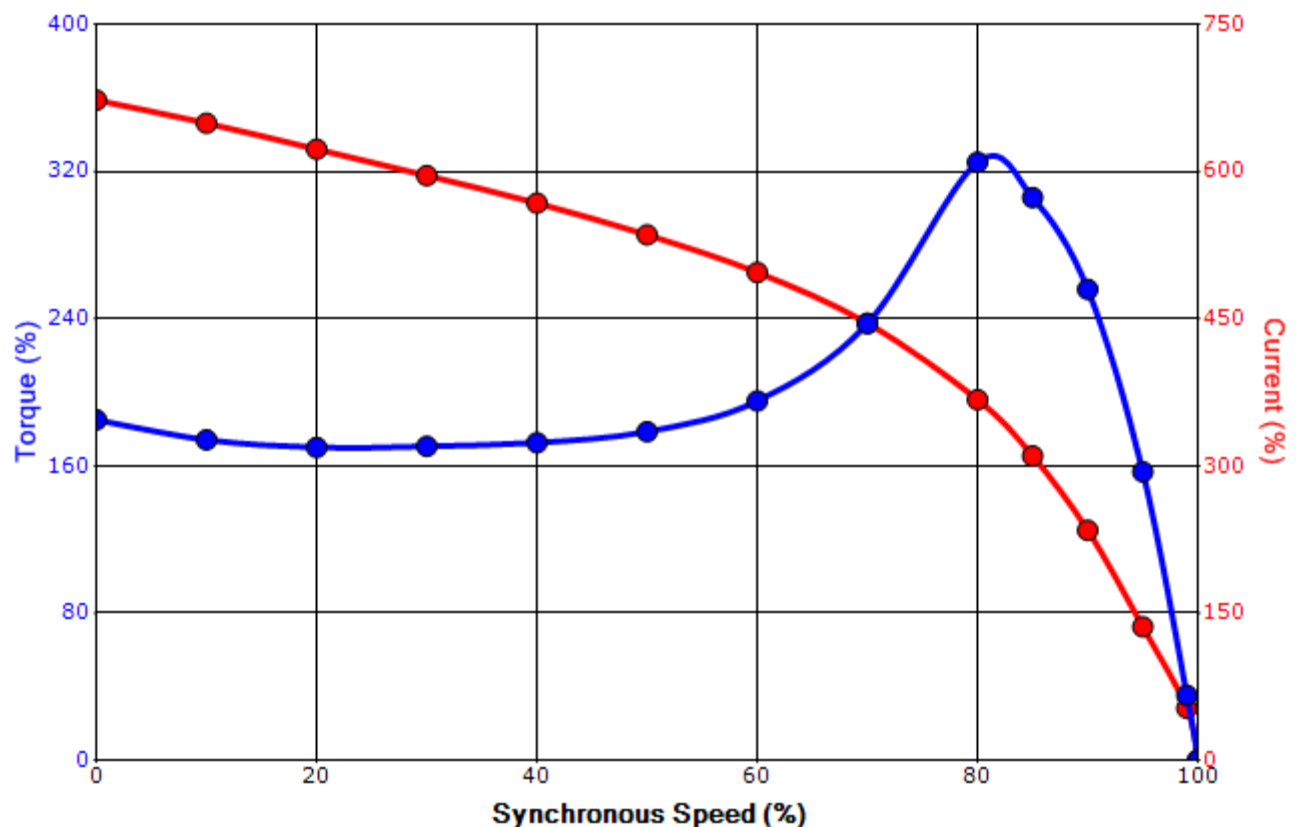
Engineering	garce	Doc. Written By	D. Suarez	Doc.# / Rev	MPCF-1119 / 0
Engr. Date	8/21/2015	Doc. Approved By	M. Campbell	Doc. Issued	6/8/2011

SPEED TORQUE/CURRENT CURVE

Model: 0056XDSC44A-P

HP	kW	Pole	FL RPM	Frame	Voltage	Hz	Phase	FL Amps
5	3.7	6	1160	215TC	575	60	3	5.50
Enclosure	IP	Ins. Class	S.F.	Duty	NEMA Nom. Eff.	NEMA Design	kVA Code	Ambient (°C)
TEFC	56	F	1.15	CONT	89.5	B	J	40 C
Locked Rotor Amps	Rotor wk ² Inertia (lb-ft ²)	Torque						
		Full Load (lb-ft)	Locked Rotor (%)	Pull Up (%)		Break Down (%)		
36	1.32	22.6	185	175		325		

Design Values



Customer			wk ² Load Inertia (lb-ft ²)	-
Customer PO			Load Type	-
Sales Order			Voltage (%)	100
Project #			Accel. Time	-

Tag:

All characteristics are average expected values.

TOSHIBA INTERNATIONAL CORPORATION · HOUSTON, TEXAS U.S.A.

Engineering	garce	Doc. Written By	D. Suarez	Doc.# / Rev	MPCF-1121 / 0
Engr. Date	8/21/2015	Doc. Approved By	M. Campbell	Doc. Issued	6/8/2011

Motor Connection Diagram

3 Leads - Delta Connection



Switch L1 and L2 to reverse rotation

Each lead may consist of more than one cable.
If multiple cables represent a single lead, each one
of them will be labeled with the appropriate lead number.