

TYPICAL MOTOR PERFORMANCE DATA

Model: 0056XDSB44A-P

HP	kW	Pole	FL RPM	Frame	Voltage	Hz	Phase	FL Amps
5	3.7	6	1160	215TC	460	60	3	6.90
Enclosure	IP	Ins. Class	S.F.	Duty	NEMA Nom. Eff.	NEMA Design	kVA Code	Ambient (°C)
TEFC	56	F	1.15	CONT	89.5	B	J	40 C

Load	HP	kW	Amperes	Efficiency (%)	Power Factor (%)
Full Load	5	3.7	6.9	89.6	78.2
¾ Load	3.75	2.8	5.3	89.7	73.2
½ Load	2.50	1.9	4.3	88.2	63.0
¼ Load	1.25	0.9	3.6	80.9	39.7
No Load			3.1		5.5
Locked Rotor			45.5		45.6

Torque				Rotor wk² Inertia (lb-ft²)
Full Load (lb-ft)	Locked Rotor (% FLT)	Pull Up (% FLT)	Break Down (% FLT)	
22.6	185	175	330	1.32

Safe Stall Time(s)		Sound Pressure dB(A) @ 1M	Bearings*		Approx. Motor Weight (lbs)
Cold	Hot		DE	NDE	
42.6	30.9	-	6308C3	6308C3	190

*Bearings are the only recommended spare part(s).

Motor Options:

Mounting:C-Face Round,Shaft:T Shaft

Customer		
Customer PO		
Sales Order		
Project #		

Tag:

All characteristics are average expected values.

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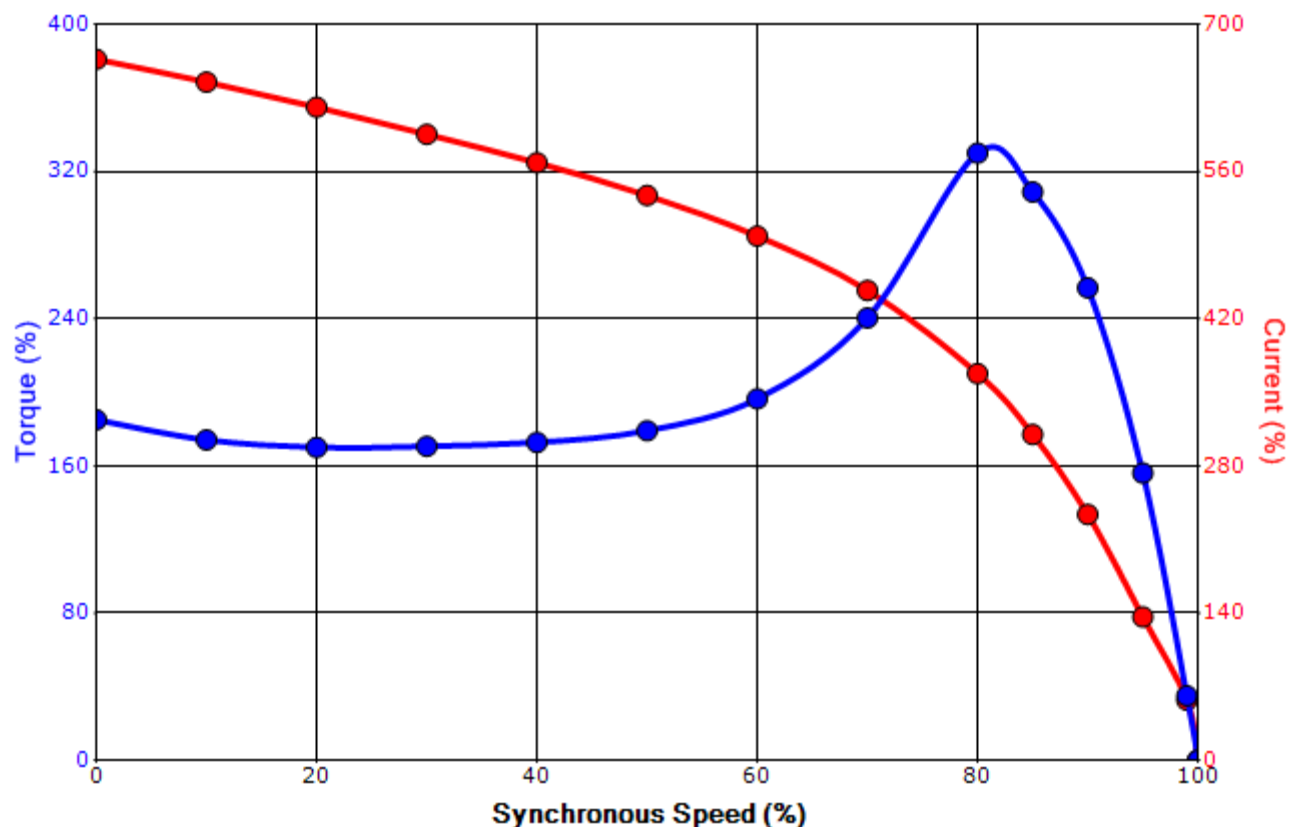
Engineering	jaustin	Doc. Written By	D. Suarez	Doc.# / Rev	MPCF-1119 / 0
Engr. Date	7/7/2014	Doc. Approved By	M. Campbell	Doc. Issued	6/8/2011

SPEED TORQUE/CURRENT CURVE

Model: 0056XDSB44A-P

HP	kW	Pole	FL RPM	Frame	Voltage	Hz	Phase	FL Amps
5	3.7	6	1160	215TC	460	60	3	6.90
Enclosure	IP	Ins. Class	S.F.	Duty	NEMA Nom. Eff.	NEMA Design	kVA Code	Ambient (°C)
TEFC	56	F	1.15	CONT	89.5	B	J	40 C
Locked Rotor Amps	Rotor wk ² Inertia (lb-ft ²)	Torque						
		Full Load (lb-ft)	Locked Rotor (%)	Pull Up (%)		Break Down (%)		
45.5	1.32	22.6	185	175		330		

Design Values



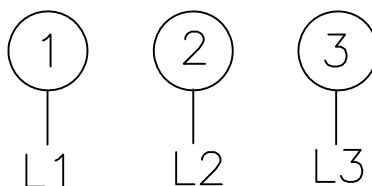
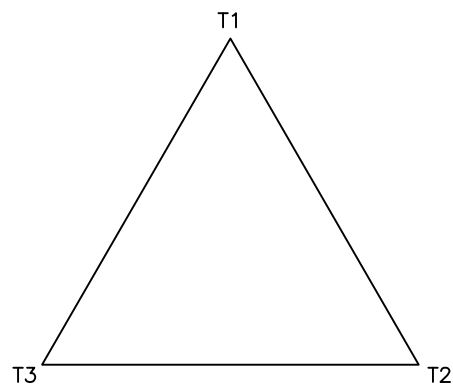
Customer			wk ² Load Inertia (lb-ft ²)	-
Customer PO			Load Type	-
Sales Order			Voltage (%)	100
Project #			Accel. Time	-

Tag:

All characteristics are average expected values.

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Motor Connection Diagram
3 Leads - Delta Connection

Switch L1 and L2 to reverse rotation

Each lead may consist of more than one cable.
If multiple cables represent a single lead, each one
of them will be labeled with the appropriate lead number.